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### 1. GENSETS: GENERators for Small Electrical and Thermal Systems (GENSETS)

Release Date: 07-16-2015 Open Date: 07-16-2015 Due Date: 08-17-2015 Close Date: 08-17-2015

PLEASE NOTE: A prior Letter of Intent is not required for this specific FOA from DOE-ARPA-E. SUMMARY The GENSETS Program – GENERators for Small Electrical and Thermal Systems – seeks to fund the development of potentially disruptive generator technologies that will enable widespread deployment of residential Combined Heat and Power (CHP) systems. Here, CHP is defined as the distributed generat ...

SBIRSTTR Department of Energy ARPA-E

### 2. 1: MOSAIC STTR

Release Date: 12-08-2014 Open Date: 12-08-2014 Due Date: 01-22-2015 Close Date: 01-22-2015

The MOSAIC (Micro-scale Optimized Solar-cell Arrays with Integrated Concentration) Program will fund potentially disruptive technologies and related system concepts to achieve new performance and cost benchmarks for solar-electric generation from photovoltaics (PV). Specifically, MOSAIC will develop novel concepts that integrate arrays of high-performan ...

STTR Department of Energy

### 3.

Release Date: 11-25-2013 Open Date: 11-25-2013 Due Date: 02-04-2014 Close Date: 02-04-2014

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### 4. 22: ADVANCED DIAGNOSTIC TECHNIQUES FOR ELECTRIC POWER SYSTEMS – FAULT DETECTION

Release Date: 11-25-2013 Open Date: 11-25-2013 Due Date: 02-04-2014 Close Date: 02-04-2014

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### 5. OSD14.1-AU1: Biometrics for Human-machine Team Feedback in Autonomous Systems

Release Date: 11-20-2013 Open Date: 12-20-2013 Due Date: 01-22-2014 Close Date: 01-22-2014

This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop and use biometrics that provides feedback about the status of human-machine team in autonomous systems. DESCRIPTION: Intense workload and short deadlines place a great deal of stress on warfighters applying computer systems to complete their mission. Biometric techniques show

promise for detecting variatio ...

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**6. [OSD14.1-AU2: Evaluating the Performance and Progress of Learning-enabled Systems](#)**

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop methodology to evaluate and measure the performance and progress for learning enabled systems. DESCRIPTION: A long term goal of machine learning is to develop systems that learn complex behaviors with minimal human oversight. However, future systems that incorporate learning strategies will not necessarily ...

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**7. [OSD14.1-AU3: Evaluating Mixed Human/Robot Team Performance](#)**

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop methodology to evaluate mixed human/robot team performance DESCRIPTION: Introducing robotic assets to a military or civilian unit should increase the level of performance for the team. We evaluate human teams by scoring their performance on specific tasks; they can be a single score for the team, or an aggr ...

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**8. [OSD14.1-AU4: Safety Testing for Autonomous Systems in Simulation](#)**

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: The Army is interested in adding autonomy to its vehicle convoys [1], but how can we certify that these autonomous algorithms are safe? Currently, live testing of full vehicle systems is the only acceptable method, but even after hundreds of hours of successful live testing, a single hidden failure point in the algor ...

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**9. [OSD14.1-AU5: Distributed Visual Surveillance for Unmanned Ground Vehicles](#)**

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

This topic is supported under National Robotics Initiatives (NRI). OBJECTIVE: Develop a system to identify, classify, and analyze visual data from unmanned ground vehicles and stationary visual surveillance sources to enable real-time on-board decisions and system-

wide planning regarding route, speed, and tasks. DESCRIPTION: Distributed visual surveillance has a major role in the future of ...

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### **10. [OSD14.1-IA1: Obfuscation to Thwart Un-Trusted Hardware](#)**

Release Date: 11-20-2013Open Date: 12-20-2013Due Date: 01-22-2014Close Date: 01-22-2014

OBJECTIVE: To develop innovative methods for mutating or obfuscating the processes of network security appliances or tactical communication systems. To make the path of the processes and data through hardware non deterministic, thereby thwarting any supply chain attacks that rely on the deterministic nature of computing to exfiltrate data and compromise operations. To mask the data and processes s ...

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